Cylindrical Inductive Long-Distance Proximity Sensors

# **PRD Series (IO-Link)** INSTRUCTION MANUAL

#### TCD210174AG

**Autonics** 

Thank you for choosing our Autonics product.

Read and understand the instruction manual and manual thoroughly before using the product.

For your safety, read and follow the below safety considerations before using. For your safety, read and follow the considerations written in the instruction manual, other manuals and Autonics website.

Keep this instruction manual in a place where you can find easily. The specifications, dimensions, etc. are subject to change without notice for product improvement. Some models may be discontinued without notice. Follow Autonics website for the latest information.

#### Safety Considerations

 Observe all 'Safety Considerations' for safe and proper operation to avoid hazards. -  $\underline{\Lambda}$  symbol indicates caution due to special circumstances in which hazards may occur.

Warning Failure to follow instructions may result in serious injury or death.

- 01. Fail-safe device must be installed when using the unit with machinery that may cause serious injury or substantial economic loss.(e.g. nuclear power control, medical equipment, ships, vehicles, railways, aircraft, combustion apparatus, safety equipment, crime/disaster prevention devices, etc.) Failure to follow this instruction may result in personal injury, economic loss or fire.
- 02. Do not use the unit in the place where flammable/explosive/corrosive gas, high humidity, direct sunlight, radiant heat, vibration, impact or salinity may be present.

Failure to follow this instruction may result in explosion or fire.

03. Do not disassemble or modify the unit. Failure to follow this instruction may result in fire.

04. Do not connect, repair, or inspect the unit while connected to a power source.

Failure to follow this instruction may result in fire.

05. Check 'Connections' before wiring.

Failure to follow this instruction may result in fire.

▲ Caution Failure to follow instructions may result in injury or product damage.

01. Use the unit within the rated specifications.

- Failure to follow this instruction may result in fire or product damage. 02. Use a dry cloth to clean the unit, and do not use water or organic solvent.
- Failure to follow this instruction may result in fire. 03. Do not supply power without load. Failure to follow this instruction may result in fire or product damage.

#### **Cautions during Use**

- Follow instructions in 'Cautions during Use'.
- Otherwise, it may cause unexpected accidents.
- 12 24 VDC --- power supply should be insulated and limited voltage/current or Class 2, SELV power supply device.
- Use the product, after 0.8 sec of supplying power.
- Wire as short as possible and keep away from high voltage lines or power lines, to prevent surge and inductive noise
- Do not use near the equipment which generates strong magnetic force or high frequency noise (transceiver, etc.).

In case installing the product near the equipment which generates strong surge (motor, welding machine, etc.), use diode or varistor to remove surge.

- This unit may be used in the following environments.
- Indoors (UL Type 1 Enclosure)
- Altitude max. 2,000 m
- Pollution degree 3
- Installation category II

## **Cautions for Installation**

- · Install the unit correctly with the usage environment, location, and the designated specifications.
- Do NOT impacts with a hard object or excessive bending of the wire lead-out. It may cause damage the water resistance.
- Do NOT pull the Ø 3.5 mm cable with a tensile strength of 25 N, the Ø 4 mm cable with a tensile strength of 30 N or over and the Ø 5 mm cable with a tensile strength of 50 N
- or over. It may result in fire due to the broken wire.
- When extending wire, use AWG 22 cable or over within 200 m.
- In case of IO-Link mode, the cable length between the unit and the IO-Link Master should be under 20 m.
- Factory default is push-pull N.O. mode in SIO mode.
- If logical connection (OR, AND) between sensors is required, set the output mode to NPN or PNP

#### Ordering Information

This is only for reference, the actual product does not support all combinations. For selecting the specified model, follow the Autonics website.

PRD 0 0 - 8 0	) - 6] - 6		
• Connection No mark: Cable type W: Cable connector type CM: Connector type	Power supply D: 12 - 24 VDC==		
OIA. of sensing side Number: DIA. of sensing side (unit: mm)	• Cable No mark: Standard type V: Oil resistant cable type		
Sensing distance Number: Sensing distance (unit: mm)	Communication     IL2: IO-Link COM2		
Product Components			
• Product $\times$ 1	• Nut × 2		

• Washer × 1

#### Sold Separately

• Instruction manual  $\times 1$ 

 M12 Connector cable: C□DH4-□(-□)
 Spatter protection cover: P90-M□ Fixing bracket: P90-R□

## **Communication Interface**

## IO-Link

Version	Ver. 1.1
Class	Class A
Baud rate	COM 2 (38.4 kbps)
Min. cycle time	2.3 ms
Data length	PD: 2 byte, OD: 1 byte (M-sequence: TYPE_2_2)
Vendor ID	899 (0x383)

## Software

Download the installation file and the manuals from the Autonics website.

#### atIOLink

atIOLink with purposes for setting, diagnosis, and maintenance of IO-Link device via IODD file is provided as the Port and Device Configuration Tool (PDCT). IODD (IO Device Description)

This file contains information such as manufacturer information, process data, diagnostic data, and parameter setting of a sensor using IO-Link communication. By uploading the IODD file to PDCT Software, you can check the setting and

communication data according to the user interface.

Download the IODD file from the Autonics website.

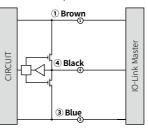
#### Circuits

1) Brown	2 White	3 Blue	④ Black
+L	I/Q <sup>01)</sup>	L-	C/Q

01) The I/Q terminal is the inverted output of the C/Q terminal In case of IO-Link mode, I/Q terminal output turns OFF.

#### IO-Link mode

• The control output mode can be switched through parameter setting.

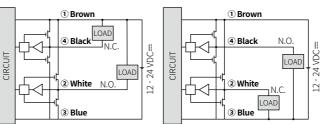


#### SIO mode

• The control output mode can be selected through load connection. Factory default

: Output type - Push-pull / Output mode - N.O.

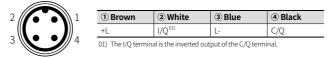
#### In case of NPN connection



In case of PNP connection

## **Connector Specification**

- For LOAD connection, follow the cable type connection.
- Fasten the connector not to shown the thread. (0.39 to 0.49 N m)
- · Fasten the vibration part with PTFE tape.



#### Functions

#### Output-related functions

- IO-Link or SIO mode
- (Parameter setting possible through software when IO-Link mode)
- Timer mode (Timer OFF (factory default) / ON Delay / OFF Delay / One Shot) • Timer time (1 to 9999 ms)
- Too close target detection and unstable detection alarm
- Control output (Push-Pull / NPN / PNP)
- Output mode (N.O. (Normally Open) / N.C. (Normally Closed))
- Operating time save

#### Monitoring functions

- Power monitoring
- Output disconnection detection
- Coil disconnection detection
- Over temperature detection
- Operating time alarm
- Disturbance signal detection

## Specifications

Installation	Flush type							
Model	PRD 12-4D- IL2	PRD[]18-7D-[]-IL2	PRD 30-15D					
DIA. of sensing side	Ø 12 mm	Ø 18 mm	Ø 30 mm					
Sensing distance	4 mm	7 mm	15 mm					
Setting distance	0 to 2.8 mm	0 to 10.5 mm						
Hysteresis	$\leq$ 10 % of sensing distanc	≤ 10 % of sensing distance						
Standard sensing target: iron	$12 \times 12 \times 1$ mm	20 × 20 × 1 mm	$45 \times 45 \times 1$ mm					
Response frequency <sup>01)</sup>	500 Hz	250 Hz	100 Hz					
Affection by temperature	$\leq$ $\pm$ 10 % for sensing dist	ance at ambient temperature	≘ 20 °C					
Indicator <sup>02)</sup>	IO-Link mode, SIO mode (	IO-Link mode, SIO mode (varies by mode)						
IO-Link mode	Communication indicator (flashing green), operation indicator (orange), Abnormal detect indicator (cross-flashing green, orange)							
SIO mode		ge), stable indicator (green), (cross-flashing green, orang	e)					
Approval	C € ዸ፝፝፝ዿ ‹ඖං ගත 🗞 IO-Link							

01) The response frequency is the average value. The standard sensing target is used and the width is set as 2 times of the standard sensing target, 1/2 of the sensing distance for the distance.
02) In case of SIO mode, use the device within the range where the stable indicator (green) is ON. If the sensing target is in the too close detection distance, the stable indicator turns OFF, but it is in a stable

In case of IO-Link mode, use the device within the range where unstable detection (Byte0\_bit6) turns 0. If the sensing target is in the too close detection distance, the too close detection (Byte0\_bit5) is 1, but it is a stable detection state.

Installation	Non-flush type						
Model	PRD 12-8D- IL2	PRD[]18-14D-[]-IL2	PRD 30-25D IL2				
DIA. of sensing side	Ø 12 mm	Ø 18 mm	Ø 30 mm				
Sensing distance	8 mm	14 mm	25 mm				
Setting distance	0 to 5.6 mm	0 to 9.8 mm	0 to 17.5 mm				
Hysteresis	≤ 10 % of sensing distance						
Standard sensing target: iron	$25 \times 25 \times 1 \text{mm}$	$40 \times 40 \times 1 \text{mm}$	$75 \times 75 \times 1 \text{ mm}$				
Response frequency <sup>01)</sup>	400 Hz	200 Hz	100 Hz				
Affection by temperature	$\leq \pm$ 10 % for sensing distance at ambient temperature 20 °C						
Indicator <sup>02)</sup>	IO-Link mode, SIO mode (v	aries by mode)					
IO-Link mode	Communication indicator (flashing green), operation indicator (orange), Abnormal detect indicator (cross-flashing green, orange)						
SIO mode		Operation indicator (orange), stable indicator (green), Abnormal detect indicator (cross-flashing green, orange)					
Approval	C € 분Ķ : (원===== 🏵 IO-Link						

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Unit weight (package)	Ø 12 mm	Ø 18 mm	Ø 30 mm
Cable	$\approx$ 62 g ( $\approx$ 74 g)	≈ 97 g (≈ 115 g)	≈ 143 g (≈ 180 g)
Cable connector	≈ 37 g (≈ 67 g)	≈ 62 g (≈ 80 g)	$\approx$ 108 g ( $\approx$ 145 g)
Connector	$\approx$ 20g ( $\approx$ 49 g)	≈ 41 g (≈ 81 g)	≈ 138 g (≈ 197 g)

Power supply	12 - 24 VDC== (ripple P-P: ≤ 10 %), operating voltage: 10 - 30 VDC==
Current consumption	IO-Link mode: ≤ 25 mA, SIO mode: ≤ 20 mA
Control output	≤ 100 mA
Residual voltage <sup>01)</sup>	≤2V
Protection circuit	Surge protection circuit, output short over current protection circuit, reverse polarity protection
Insulation resistance	$\geq$ 50 M $\Omega$ (500 VDC== megger)
Dielectric strength	Between the charging part and the case: 1,000 VAC $\sim$ 50 / 60 Hz for 1 min
Vibration	1.5 mm double amplitude at frequency 10 to 55 Hz in each X, Y, Z direction for 2 hours
Shock	1000 m/s <sup>2</sup> ( $\approx$ 100 G) in each X, Y, Z direction for 3 times
Ambient temp. <sup>02)</sup>	-25 to 70 °C, storage: -25 to 70 °C (no freezing or condensation)
Ambient humi.	35 to 95 %RH, storage: 35 to 95 %RH (no freezing or condensation)
Protection rating	IP67 (IEC standard)
Connection	Cable / Cable connector / connector models
Cable spec. <sup>03)</sup>	DIA. of sensing side Ø 12 mm: Ø 4 mm, 4-wire DIA. of sensing side Ø 18 mm, Ø 30 mm : Ø 5 mm, 4-wire
Wire spec.	AWG 22 (0.08 mm, 60-core), insulator diameter: Ø 1.25 mm
Connector spec.	M12 plug connector
Material	Standard type cable (black): polyvinyl chloride (PVC), Oil resistant cable (gray): polyvinyl chloride (oil resistant PVC), case / nut: nickel plated brass, washer: nickel plated iron, sensing side: PBT

01) Load current: 100 mA cable length: 2 m

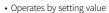
02) UL approved surrounding air temperature 40 °C

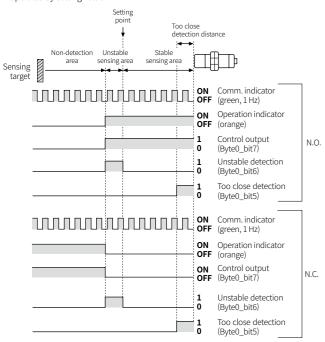
03) Cable type: 2 m, Cable connector type: 300 mm

## **Operation Timing Chart**

Refer to the Setting Distance Formula for the unstable detection area and the too close detection distance.

#### IO-Link mode





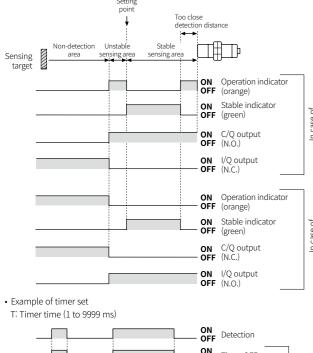
#### SIO mode

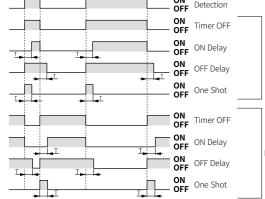
• Operates by factory default (output type - push-pull / output mode - N.O.)

 $\ensuremath{\,\cdot\,}$  In the output mode to N.C., the waveforms are reversed.

• Unstable sensing area: 70 % of max. sensing distance,

too close detection distance: 20 % of max. sensing distance. (factory default)





N.O.

V C

#### Parameter Index

#### Process data

• The current data value is displayed in real time.

Parameter	Byte0 (PD0)	Byte1 (PD1)	Format	Setting range	Description
Detection Level	-	7 to 0	Uinteger	0 to 255	Outputs the detection signal value as specific 8 bit.
Warning	4	-	Boolean	0: Normal (OFF), 1: Warning (ON)	Outputs diagnosing items defined as dangerous.
Target too Close Alarm	5	-	Boolean	0: Not Close, 1: Too Close	Outputs close range detection status.
Instability Detection Alarm	6	-	Boolean	0: Stable, 1: Unstable	Outputs instability detection status.
Sensor Output	7	-	Boolean	0: OFF, 1: ON	Displays sensor's output status. (C/Q terminal)

#### Identification menu

The device's manufacturer information and sensor information is displayed.
 It includes additionally information of companies and sensors from the IO-Link standard.

Parameter	Index	Format	R/W	Description
Vendor Name	16	String	RO	Manufacturer name
Vendor Text	17	String	RO	Manufacturer description
Product Name	18	String	RO	Product name
Product ID	19	String	RO	Product ID
Product Text	20	String	RO	Product description
H/W Version	22	String	RO	Hardware version
F/W Version	23	String	RO	Firmware version
Application specific tag	24	String	RW	Application program tag

#### Observation menu

• The device setting value is displayed.

Parameter		Index	R/W	Description
Operating Hours	-	72	RO	Sensor operation time
	Detection level		RO	Current value
	Warning	1	RO	Warning
Process Data Input	Target too close alarm	40	RO	Too close detection
	Instability detection alarm	1	RO	Unstable detection
	Sensor output		RO	Sensor output

#### Parameter menu

• Product settings such as output mode and timer can be changed according to the user environment.

Parameter		Index	Sub- index	Format	R/W	Description	Setting range	Factory default
Output Catura	Mode	64	1	Uinteger	RW	Output mode	0: N.O. (Normally Open), 1: N.C. (Normally Closed)	0
Output Setup	Туре	164	2	Uinteger	RW	Output type	0: Push-Pull, 1: NPN, 2: PNP	0
Timer	Mode	66	1	Uinteger	RW	Timer mode	0: Timer OFF, 1: ON Delay, 2: OFF Delay, 3: One Shot	0
Timer	Time (ms)	00	2	Uinteger	RW	Timer time	1 to 9,999 ms	5 ms
Target too Close	-	65	-	Uinteger	RW	Margin according to the target material	0: Disable, 1: Iron 10 %, 2: Iron 20 %, 3: Iron 30 %, 4: SUS 10 %, 5: SUS 20 %, 6: SUS 30 %, 7: Aluminum 10 %, 8: Aluminum 20 %	2
Instability Detection Alarm	-	68	-	Uinteger	RW	Output timing when instable detection	0: 0 ms, 1: 10 ms, 2: 50 ms, 3: 100 ms, 4: 300 ms, 5: 500 ms, 6: 1000 ms	4
Operating Hours Alarm Setting	-	74	-	Uinteger	RW	Operating Hours Alarm Setting	0 to 131,071 hour	100,000
Restore Factory Settings	-	2	-	Uinteger	WO	Factory default reset	130: Restore factory setting	-
Data Storage Lock	-	12	2	Record	RW	Data storage locked between IO-Link Master- Device	0: false, 1: true	0

#### Diagnosis Menu

The information about problems encountered during sensor operation is displayed.

Parameter			Format	R/W	Description
Operating Hours	-	72	Uinteger	RO	Sensor operation time
Detection Level			Uinteger	RO	Current value
Process Data Input Instabil Alarm	Warning	1	Boolean	RO	Warning
	Target too Close Alarm	40	Boolean	RO	Too close detection
	Instability Detection Alarm		Boolean	RO	Unstable detection
	Sensor Output	]	Boolean	RO	Sensor output
Detailed Device Status	-	37	Record	RO	Sensor detailed status

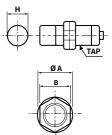
#### Events

• When the corresponding error occurs, the abnormal indicator flashes.

Event name	Event code	Туре	Description	
	6145 (0x1801)	Coil Disconnection	Coil disconnection detection warning	
	6146 (0x1802)	Short Circuit	Overcurrent detection warning	
	6147 (0x1803)	Over Temperature	Overheat detection warning	
Warning	6148 (0x1804)	Supply Under Voltage	Low voltage detection warning	
	6149 (0x1805)	Operation Time Alarm	Operation time alarm warning	
	6150 (0x1806)	Disturbance Error	Disturbance signal detection warning	
	6152 (0x1808)	EEPROM Error	EEPROM error warning	
Error	6151 (0x1807)	Parameter Setting Error	Parameter setting error	

## **Cut-out Dimensions**

• Unit: mm, For the detailed drawings, follow the Autonics website.



	Ø 12 mm	Ø 18 mm	Ø 30 mm
Mounting hole (H)	Ø 12.5 $^{+0.5}_{0}$	Ø 18.5 $^{+0.5}_{0}$	Ø 30.5 +0.5 0
TAP	M12×1	M18×1	M30×1.5

	Ø 12 mm	Ø 18 mm	Ø 30 mm
ØA	21	29	42
В	17	24	35

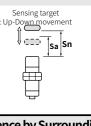
## **Setting Distance Formula**

Detecting distance can be changed by the shape, size or material of the target.

For stable sensing, install the unit within the 70 % of sensing distance.

Setting distance (Sa)

= Sensing distance (Sn) × 70 %





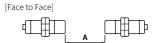
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## Mutual-interference & Influence by Surrounding Metals

#### Mutual-interference

When plural proximity sensors are mounted in a close row, malfunction of sensor may be caused due to mutual interference.

Therefore, be sure to provide a minimum distance between the two sensors, as below table.

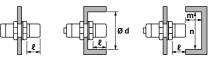






## Influence by surrounding metals

When sensors are mounted on metallic panel, it must be prevented sensors from being affected by any metallic object except target. Therefore, be sure to provide a minimum distance as below chart.



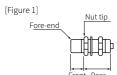
(Unit: mm)

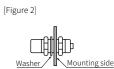
Ø 12 mm		Ø 18 mm		Ø 30 mm	
Flush	Non-flush	Flush	Non-flush	Flush	Non-flush
25	120	50	200	110	350
25	100	35	110	90	300
2.5	15	3.5	14	6	20
18	40	27	70	45	120
12	20	24	40	45	90
18	40	27	70	45	120
	Flush           25           25           2.5           18           12	Flush         Non-flush           25         120           25         100           25         15           18         40           12         20	Flush         Non-flush         Flush           25         120         50           25         100         35           25         15         3.5           18         40         27           12         20         24	Flush         Non-flush         Flush         Non-flush           25         120         50         200           25         100         35         110           25         15         3.5         14           18         40         27         70           12         20         24         40	Flush         Non-flush         Flush         Non-flush         Flush           25         120         50         200         110           25         100         35         110         90           25         15         3.5         14         6           18         40         27         70         45           12         20         24         40         45

## **Tightening Torque**

Use the provided washer to tighten the nuts.

The tightening torque of the nut varies with the distance from the fore-end. [Figure 1] If the nut tip is located at the front of the product, apply the front tightening torque. The allowable tightening torque table is for inserting the washer as [Figure 2].





	Ø 12 mm		Ø 18 mm		Ø 30 mm	
side Strength	Flush	Non-flush	Flush	Non-flush	Flush	Non-flush
Front size	13 mm	7 mm	-	-	26 mm	12 mm
Front torque	6.37 N m		14.7 N m		49 N m	
Rear torque	11.76 N m		14.7 N m		78.4 N m	

